Lilac: A Modal Separation Logic for Conditional Probability

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https://johnm.li/lilac.pdf

































Is my car safe?











Is my car safe?

Is this decision fair?











Is my car safe?

Is this decision fair? Is my result significant?











• Reasoning should be modular:





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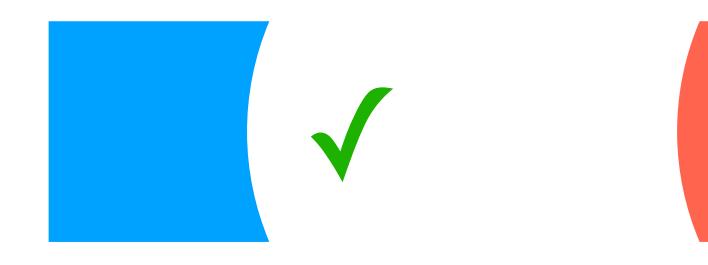


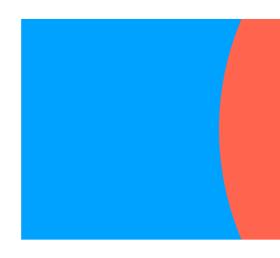




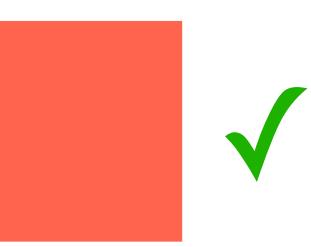


• Reasoning should be modular:













Independence arises frequently and naturally:



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weights = np.random.rand(1000)



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weights = np.random.rand(1000) weights[0], ..., weights[999] ~ Unif[0,1] mutually independent



Independence arises frequently and naturally:

result = np.mean(data)





Independence arises frequently and naturally:

if each data[i] is an independent estimate of v...

result = np.mean(data)

...then result is a more accurate estimate of v





- Independence arises frequently and naturally.
- Idea: capture independence using separation logic





- x = new 0;
- y = new 1;



 $y = (x \mapsto 0)$

- x = new 0;
- y = new 1;
- $(x \mapsto 0) * (y \mapsto 1)$



- x = new 0;
- y = new 1;
- $(x \mapsto 0) \quad * \quad (y \mapsto 1)$ x and y point to disjoint heap locations



 $\frac{\{P\} \ e \ \{x . Q(x)\}}{\{P * F\} \ e \ \{x . Q(x) * F\}}$ (Frame)

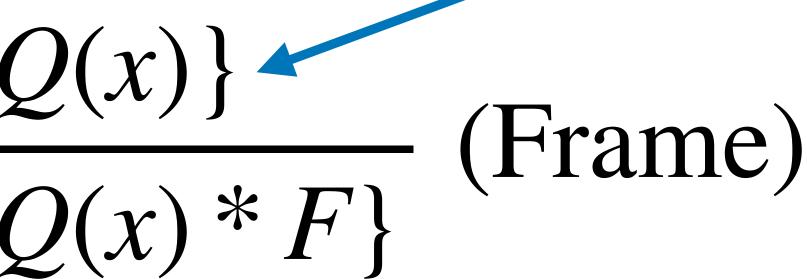


When verifying *e*... $\{P\} \ e \ \{x . Q(x)\} \\ \{P * F\} \ e \ \{x . Q(x) * F\} \ (Frame)$



When verifying *e*... {*P*} *e* {*x*. *Q*(*x*)} {*P***F*} *e* {*x*. *Q*(*x*)**F*} (Frame)

... I can ignore disjoint subheaps F







... I can ignore disjoint subheaps FWhen verifying *e*... $\{P\} \ e \ \{x . Q(x)\} \\ \hline \{P * F\} \ e \ \{x . Q(x) * F\} \ \text{(Frame)}$

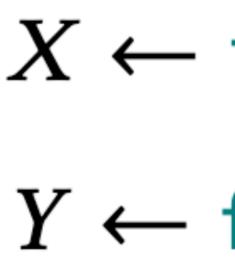
This has enabled modular heap-based reasoning at scale.¹

¹C. Calcagno and D. Distefano. Infer: An automatic program verifier for memory safety of C programs. NFM 2011.





Lilac's separation is about independence



 $X \leftarrow \mathsf{flip} 1/2;$ $Y \leftarrow \mathsf{flip} 1/2;$



Lilac's separation is about independence

 $X \leftarrow \mathsf{flip} 1/2;$ $Y \leftarrow \mathsf{flip} 1/2;$ $X \sim \text{Ber}(1/2) * Y \sim \text{Ber}(1/2)$



Lilac's separation is about independence

X and Y are independent random variables

 $X \leftarrow \mathsf{flip} 1/2;$ $Y \leftarrow \mathsf{flip} 1/2;$ $X \sim \text{Ber}(1/2) * Y \sim \text{Ber}(1/2)$



New in Lilac

10

New in Lilac: a simple frame rule

11

New in Lilac: a simple frame rule

 $\frac{\{P\} \ e \ \{x . Q(x)\}}{\{P * F\} \ e \ \{x . Q(x) * F\}}$ (Frame)

New in Lilac: a simple frame rule

Just like in ordinary separation logic!

 $\frac{\{P\} \ e \ \{x . Q(x)\}}{\{P * F\} \ e \ \{x . Q(x) * F\}}$ (Frame)

11

12

weights = np.random.rand(1000)

weights[0], ..., weights[999] ~ Unif[0,1] mutually independent



weights = np.random.rand(1000) $(weights[0] \sim Unif[0,1]) * \cdots * (weights[999] \sim Unif[0,1])$



- weights = np.random.rand(1000)
- $(weights[0] \sim Unif[0,1]) * \cdots * (weights[999] \sim Unif[0,1])$

Inexpressible in prior work



- weights = np.random.rand(1000) $(\texttt{weights[0]} \sim \texttt{Unif[0,1]}) * \cdots * (\texttt{weights[999]} \sim \texttt{Unif[0,1]})$

Completely captures independence (Lemma 2.5)





result = np.mean(data)

...then result is a more accurate estimate of v

if each data[i] is an independent estimate of v...



- if each data[i] independent and for all *i* we have $\mathbb{E}[data[i]] = v$ and $Var(data[i]) \leq \varepsilon...$
 - result = np.mean(data)

...then result is a more accurate estimate of v



- if each data[i] independent and for all *i* we have $\mathbb{E}[data[i]] = v$ and $Var(data[i]) \leq \varepsilon$...
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if $\mathbb{E}[\text{data}[i]] = v \text{ and } \text{Var}(\text{data}[i]) \le \varepsilon \dots$ $0 \le i < |\text{data}|$

result = np.mean(data)



if $\bigvee_{0 \le i < |\text{data}|} \left(\mathbb{E}[\text{data}[i]] = v \text{ and } \text{Var}(\text{data}[i]) \le \varepsilon \right) \dots$

result = np.mean(data)



if $\mathbb{E}[\text{data}[i]] = v \text{ and } \text{Var}(\text{data}[i]) \le \varepsilon$... $0 \le i < |\text{data}|$

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Ordinary expectation and variance



if $\mathbb{E}[\text{data}[i]] = v \text{ and } \text{Var}(\text{data}[i]) \le \varepsilon$... $0 \le i < |\text{data}|$

result = np.mean(data)

⇒ textbook proofs remain textbook





Probability spaces are the heaps of probability theory.





$X \sim \text{Ber}(1/2)$



$X \sim \text{Ber}(1/2)$ means $\Pr[X = \text{true}] = \Pr[X = \text{false}] = 1/2$



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This hides a lot of machinery...

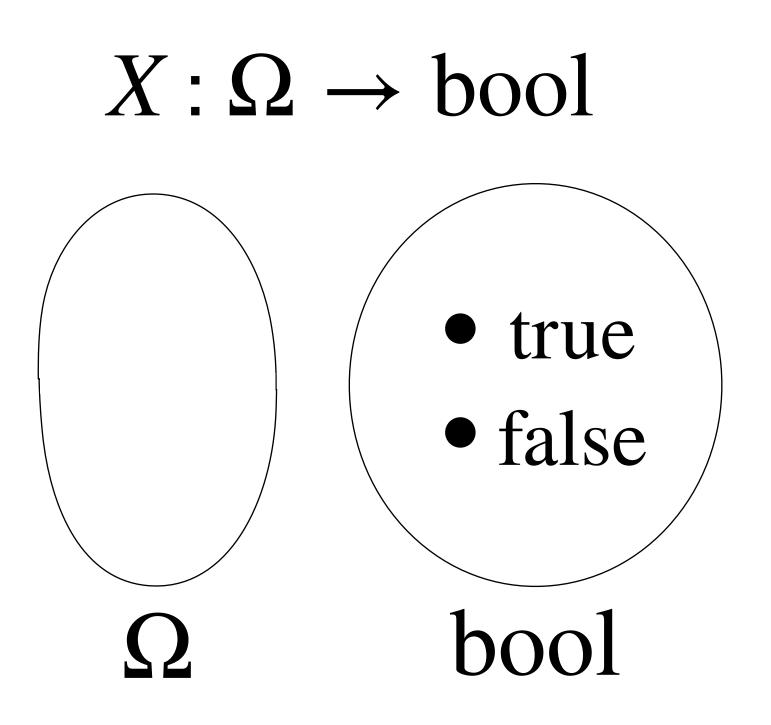




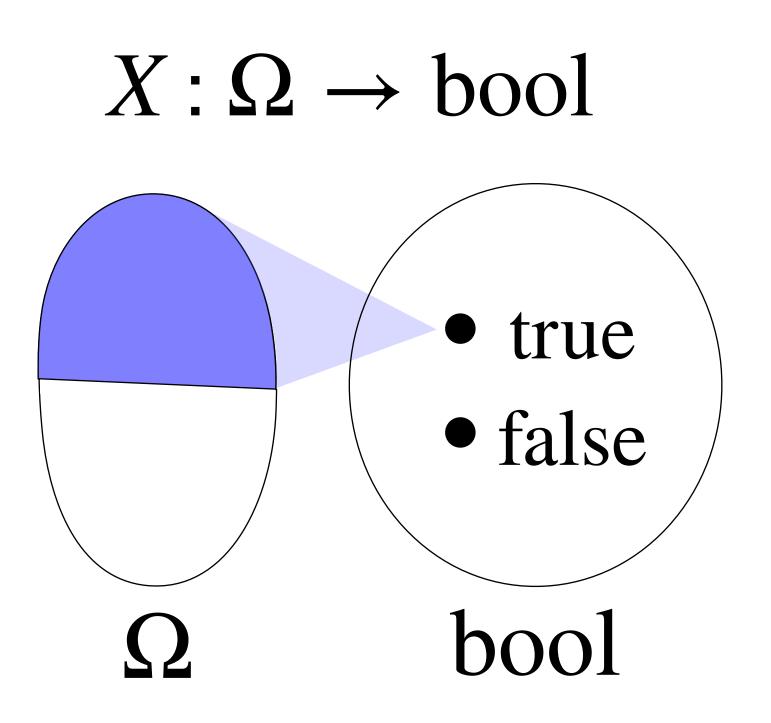
 $X \sim \text{Ber}(1/2)$ really means...

Ω

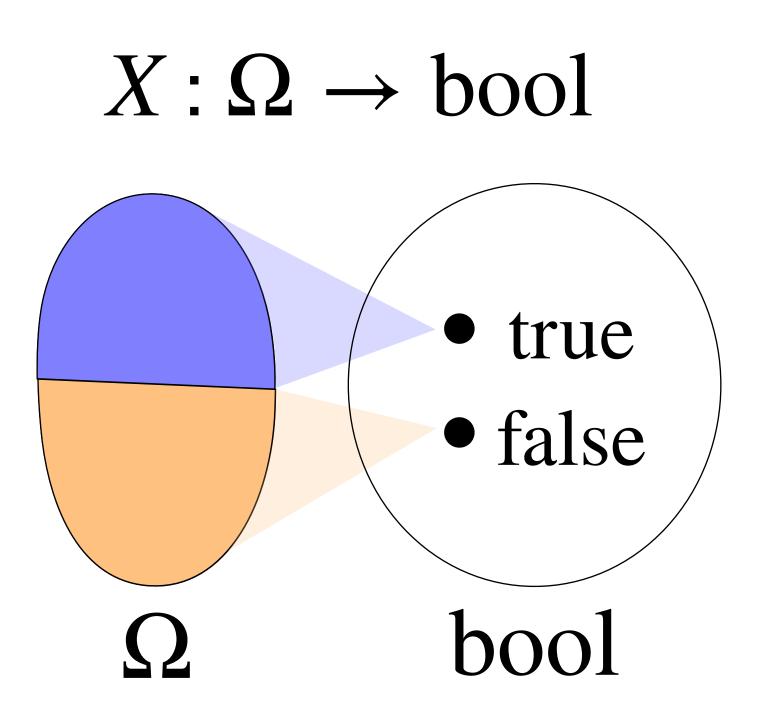






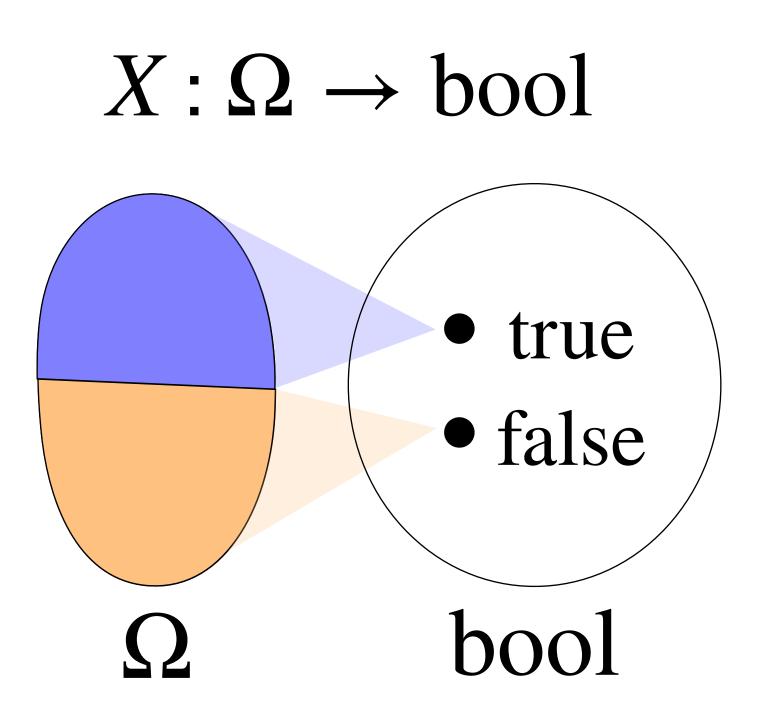








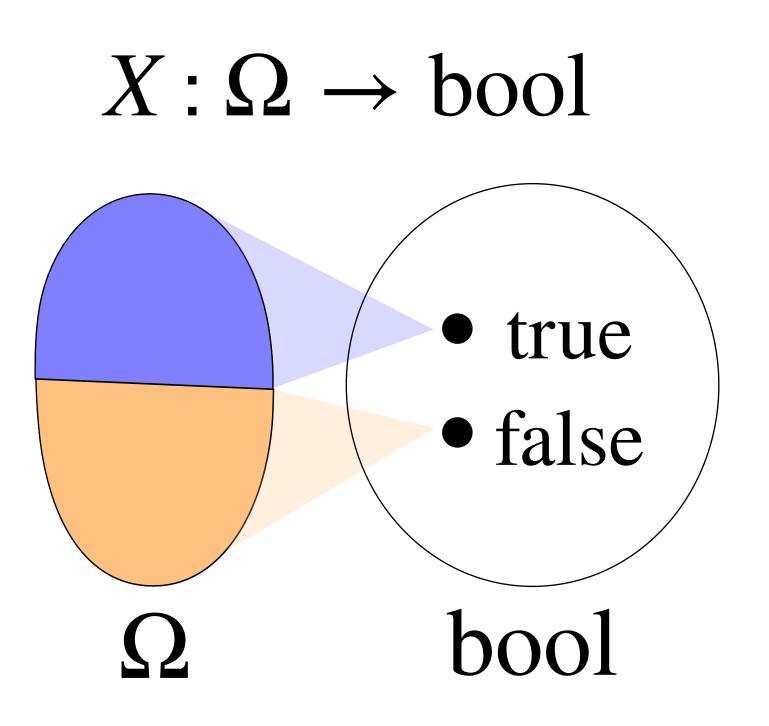
 $X \sim \text{Ber}(1/2)$ really means...



μ : events \rightarrow [0,1]



 $X \sim \text{Ber}(1/2)$ really means...

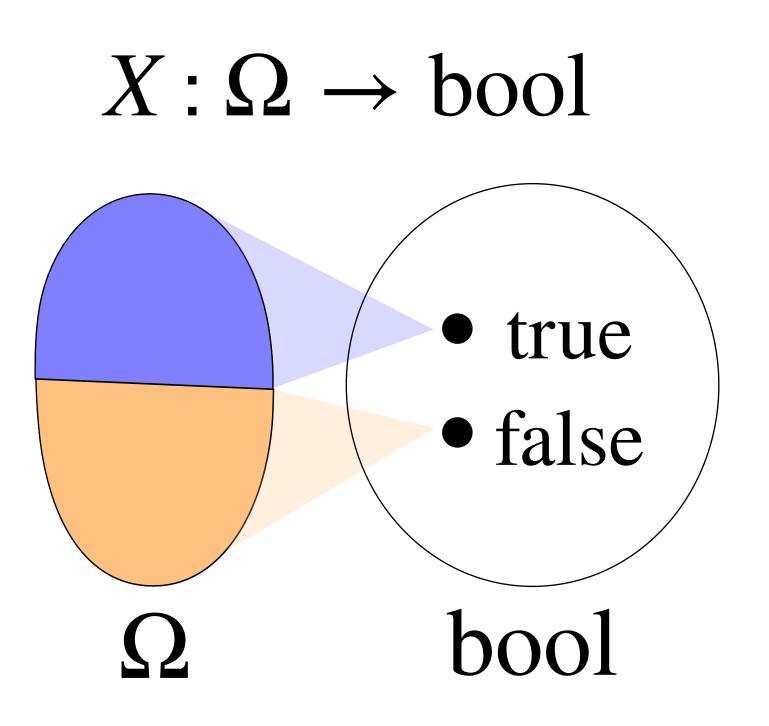


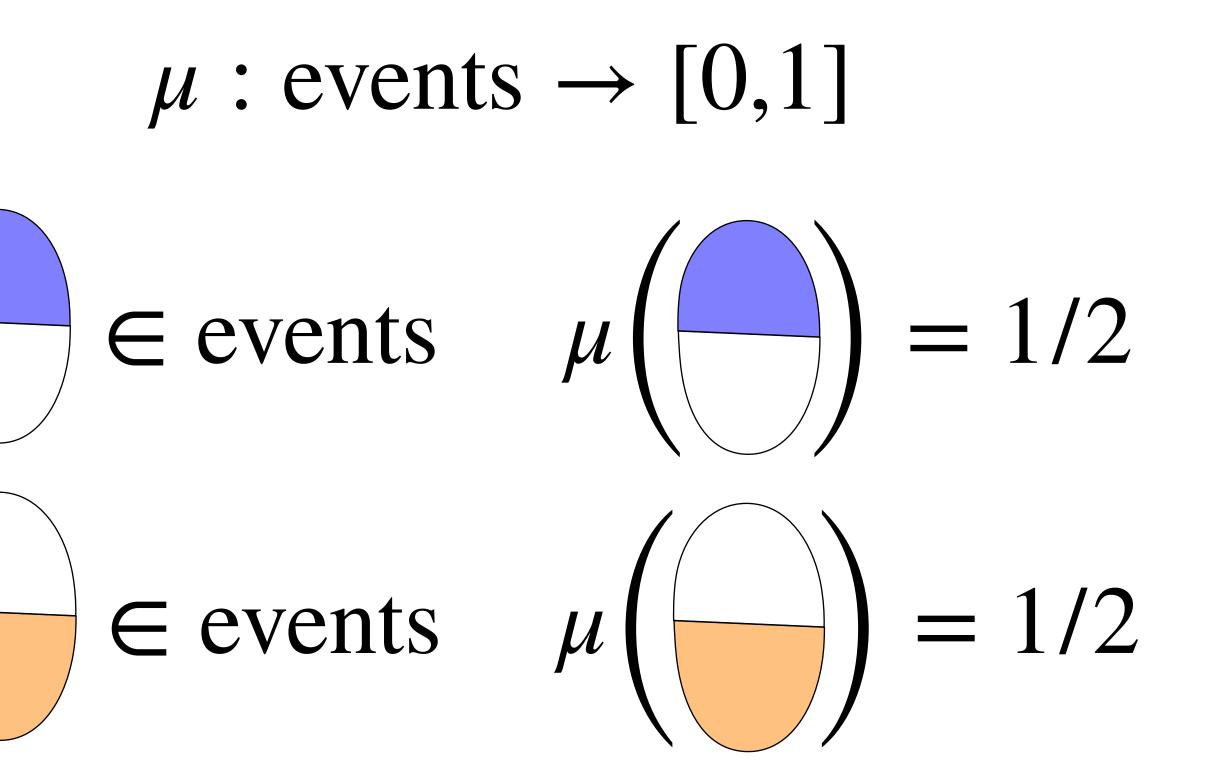
μ : events \rightarrow [0,1]

E events

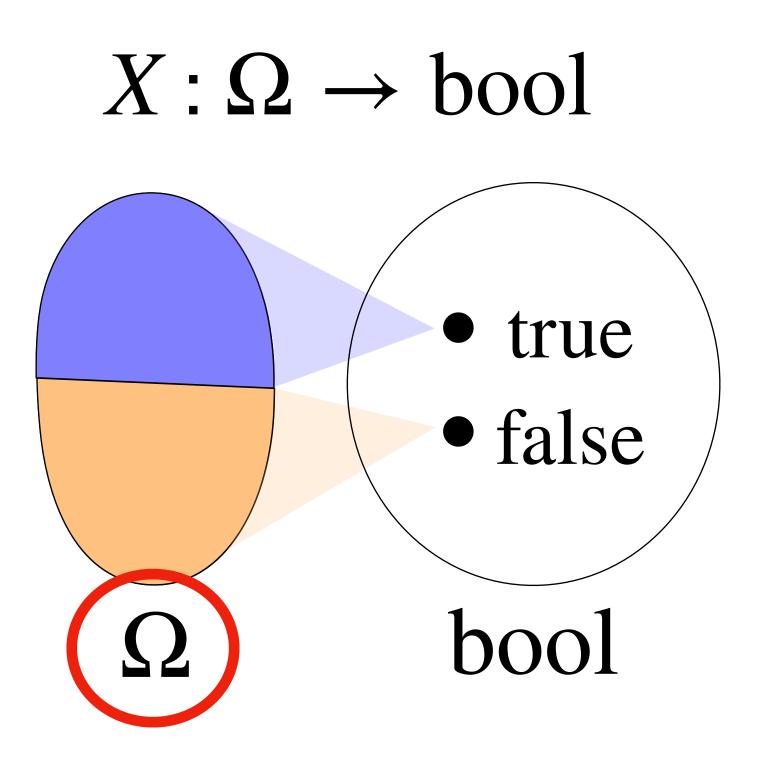
∈ events

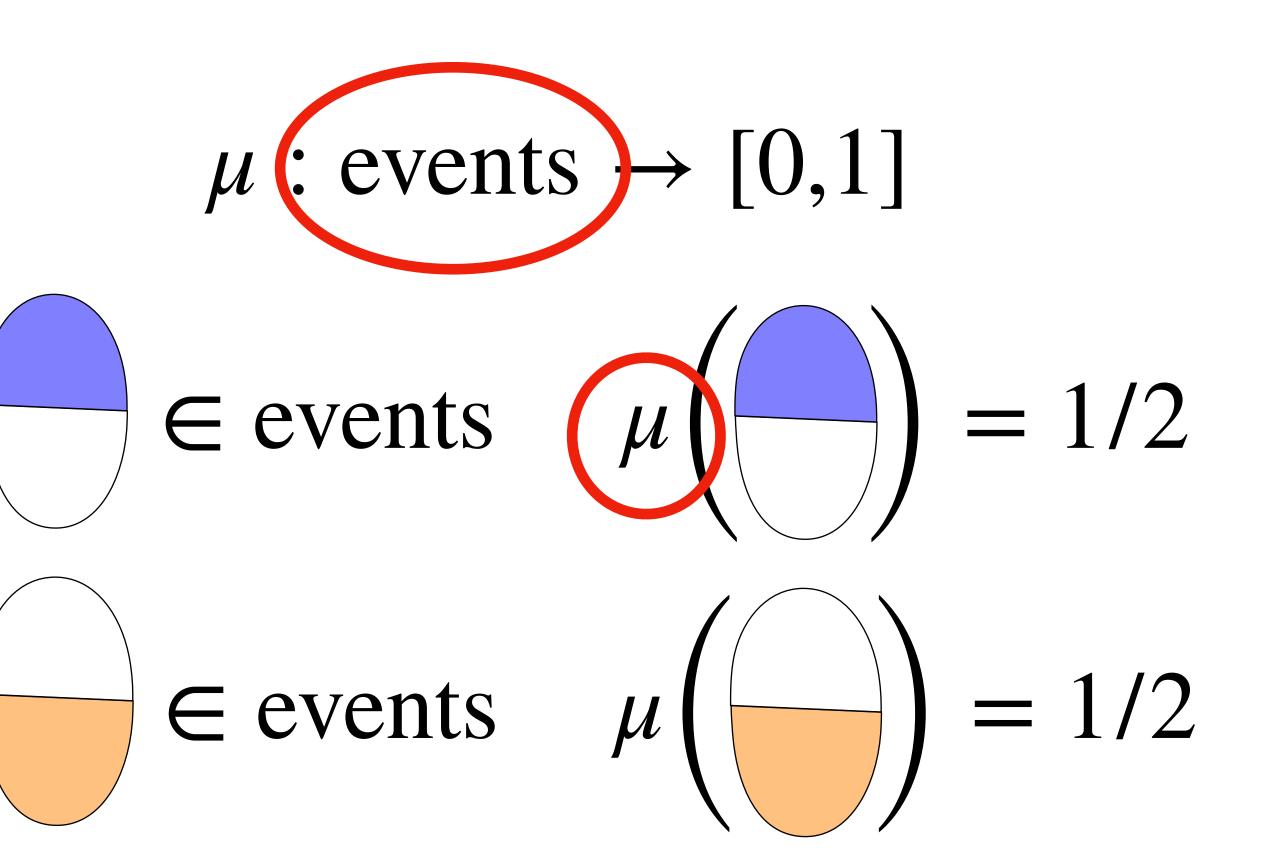








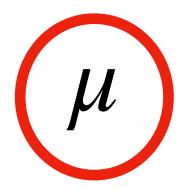










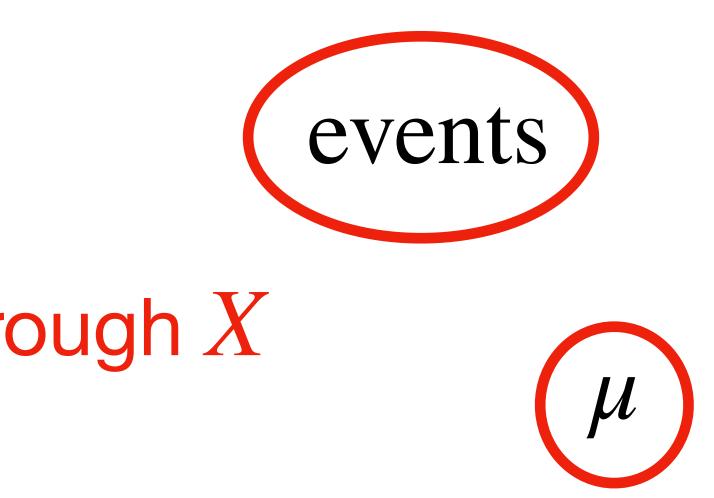




$X \sim \text{Ber}(1/2)$ really means...

Only accessed indirectly through X



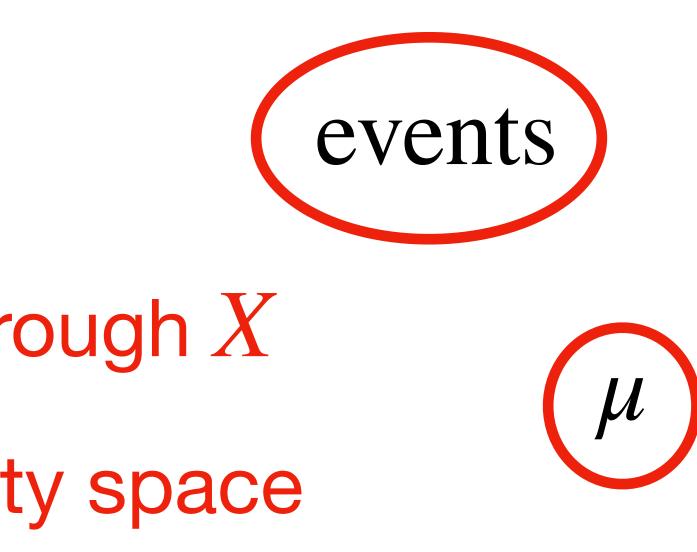




 $X \sim \text{Ber}(1/2)$ really means...

Only accessed indirectly through XTogether, form a probability space

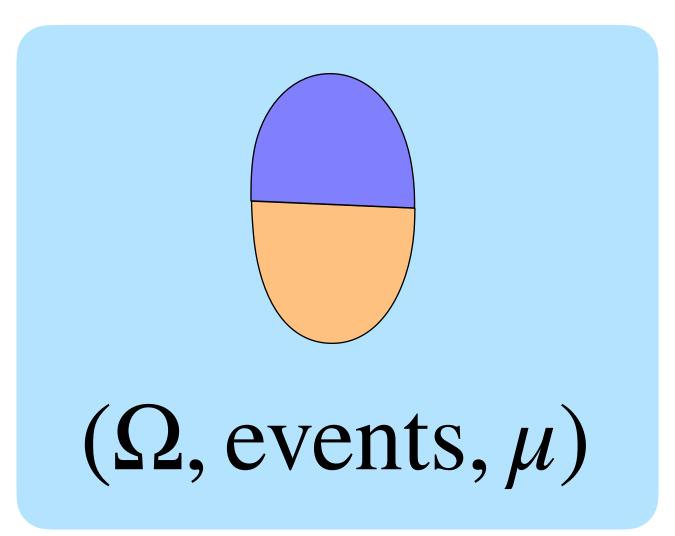






Probability theory

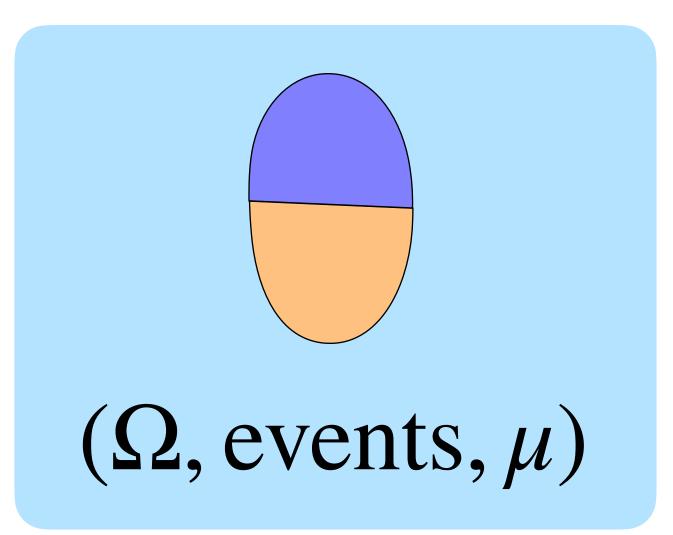






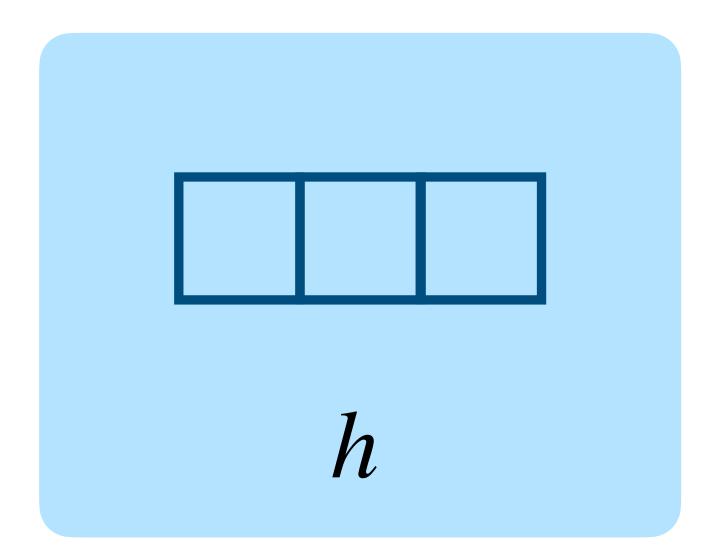
Probability theory





Mutable references







Probability spaces are the heaps of probability theory.



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x = new 0;

y = new 1;



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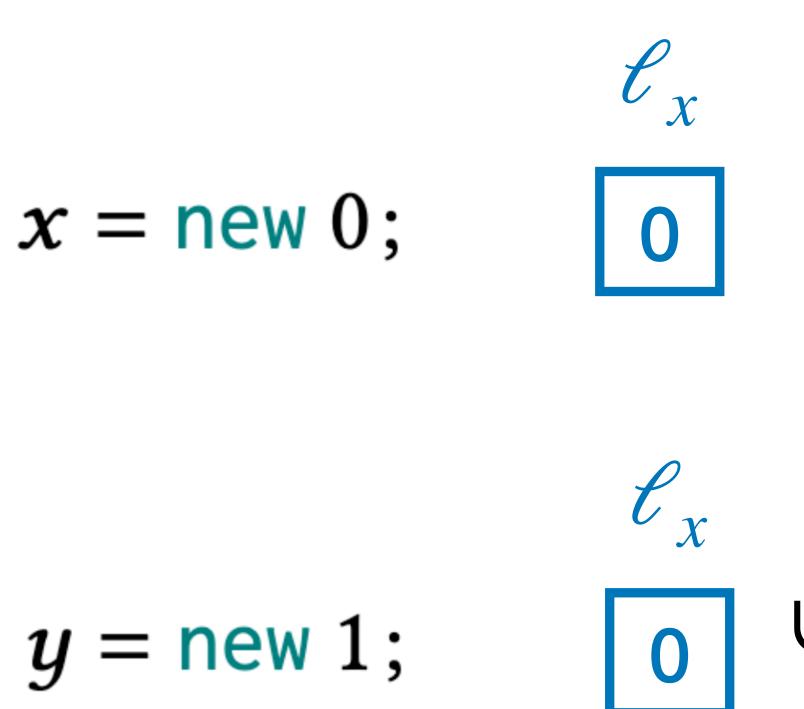
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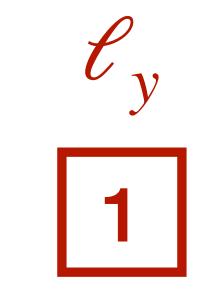






Probability spaces are the heaps of probability theory.





 \forall



Probability spaces are the heaps of probability theory.

$X \leftarrow \mathsf{flip} 1/2;$

$Y \leftarrow \mathsf{flip} 1/2;$



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X

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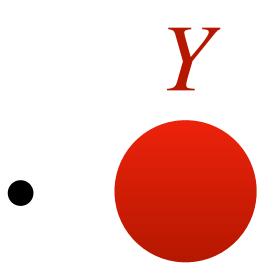


Probability spaces are the heaps of probability theory.

$X \leftarrow \mathsf{flip} 1/2;$

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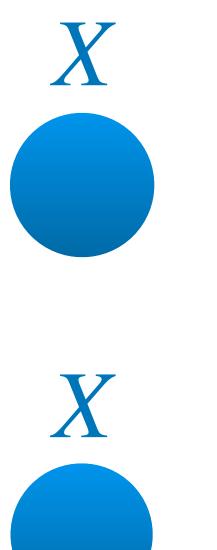




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$X \leftarrow \mathsf{flip} 1/2;$

$Y \leftarrow \mathsf{flip} 1/2;$



independent combination ("disjoint union for spaces")

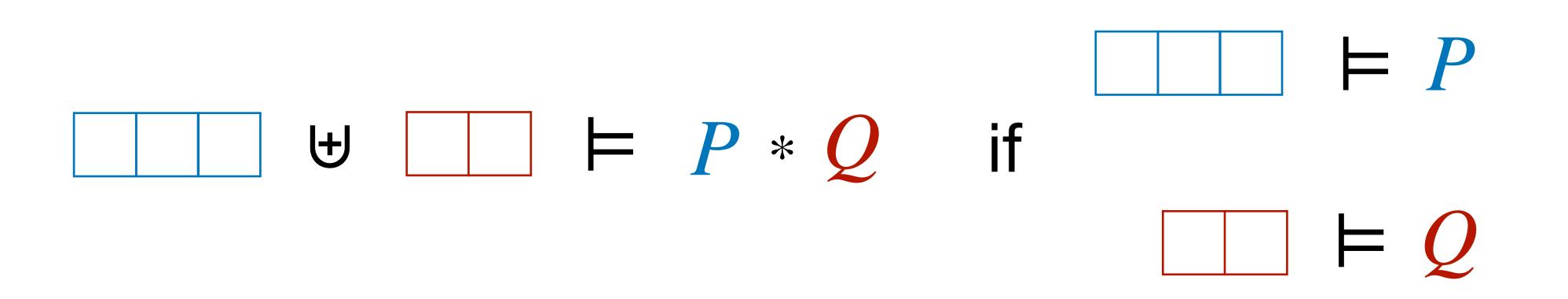


- Probability spaces are the heaps of probability theory.
- Separating conjunction decomposes probability spaces:

aps of probability theory. mposes probability spaces:



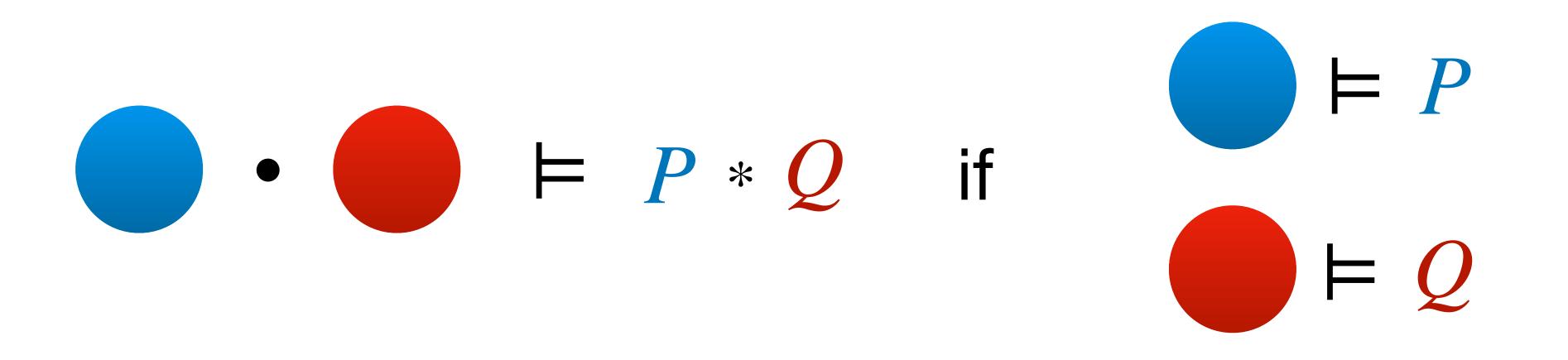
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• • $\models P * Q$ if



 $\models P$ $\models Q$







Conditioning as a modality:





Conditioning as a modality:

 $\begin{array}{c} C & P \\ x \leftarrow X \end{array}$





• Conditioning as a modality:

 $\mathbf{C} P$ $x \leftarrow X$

P holds conditional on X = x for all x





Conditioning as a modality:

$X \sim \text{Ber}(1/2) * Y \sim \text{Ber}(1/2)$





Conditioning as a modality:

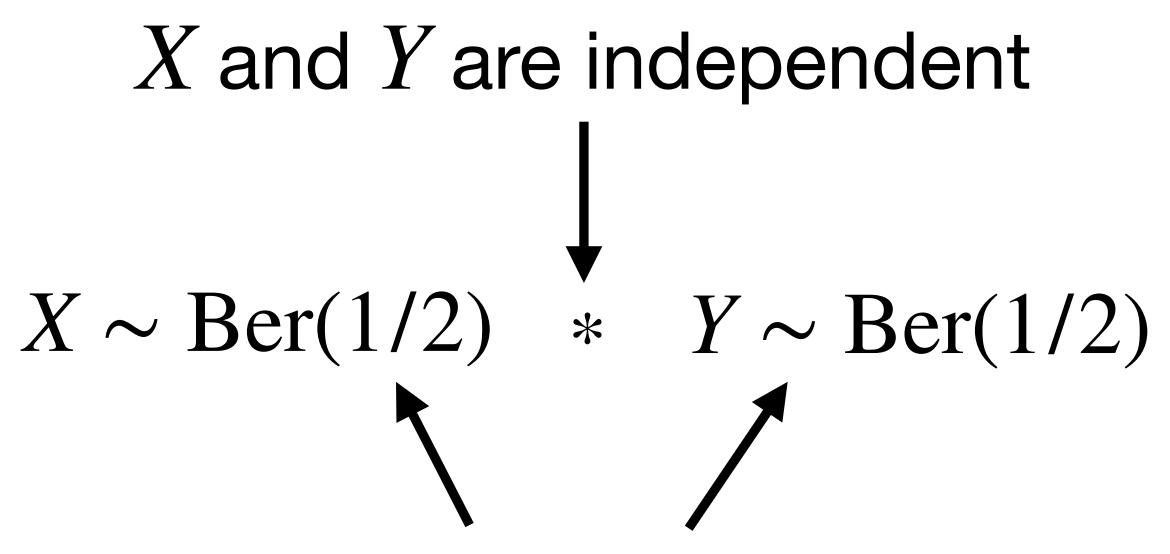
X and Y are independent

$X \sim \text{Ber}(1/2) \quad * \quad Y \sim \text{Ber}(1/2)$





Conditioning as a modality:



X and Y have distribution Ber(1/2)





• Conditioning as a modality:

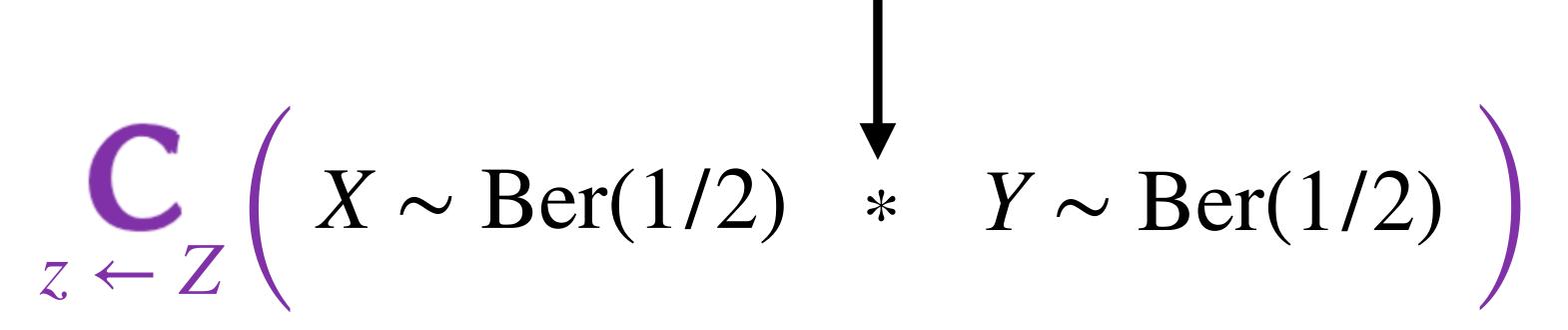
$C_{Z \leftarrow Z} \left(X \sim \text{Ber}(1/2) * Y \sim \text{Ber}(1/2) \right)$





• Conditioning as a modality:

X and Y are conditionally independent given Z







• Conditioning as a modality:

X and Y are conditionally independent given Z $\mathbf{C}_{z \leftarrow Z} \left(X \sim \operatorname{Ber}(1/2) * Y \sim \operatorname{Ber}(1/2) \right)$

X and Y have conditional distribution Ber(1/2) given Z





Conditioning as a modality:

$\Pr[E] = 1/2$ *E* has probability 1/2

$\mathbf{E}[X] = 0$

X has expectation 0





• Conditioning as a modality:

$$\sum_{x \leftarrow X} \left(\Pr[E] = 1/2 \right) \qquad E$$

$\mathbf{E}[X] = 0$

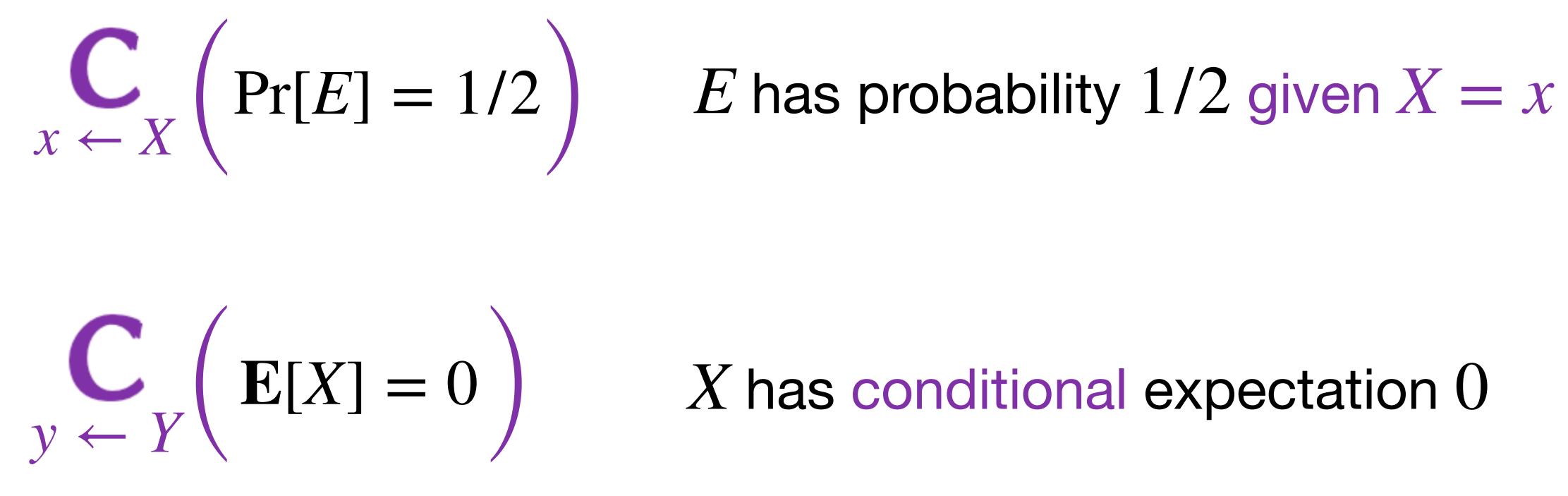
has probability 1/2 given X = x

X has expectation 0





• Conditioning as a modality:







- Conditioning as a modality
- Laws express intuitive facts and standard theorems:





- Conditioning as a modality
- Laws express intuitive facts and standard theorems:

C-TOTAL-EXPECTATION $\sum_{x \leftarrow X} \left(\mathbb{E}[E] = e \right) \land \mathbb{E}[e[X/x]] = v \vdash \mathbb{E}[E] = v$





We used Lilac to verify

- Examples from prior work (cryptographic protocols)
- A tricky weighted sampling algorithm exercising
 - Continuous random variables
 - Quantitative reasoning
 - Separation as independence
 - Conditioning modality



Also in the paper

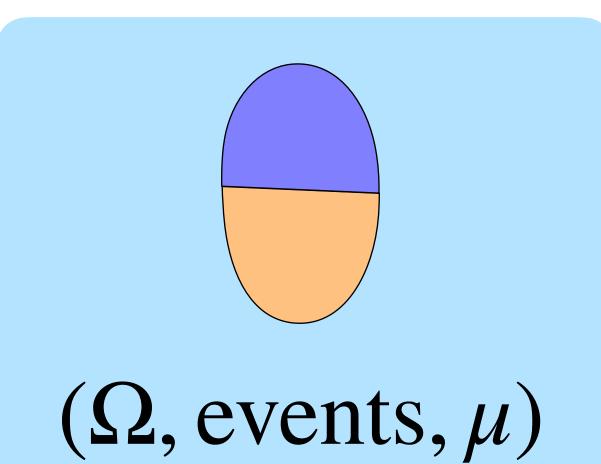
- Conditioning modality
- Ownership is measurability
- Worked examples
- Almost-sure equality $X =_{a.s.} Y$





Probability theory







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\simeq Mutable references

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